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Graph-Based Transforms based on Prediction Inaccuracy Modeling for Pathology Image Coding

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Abstract: Digital pathology images are multi giga-pixel color images that usually require large amounts of bandwidth to be transmitted and stored. Lossy compression using intra-prediction offers an attractive solution to reduce the storage and transmission requirements of these images. In this paper, we evaluate the performance of the Graph-based Transform (GBT) within the context of block-based predictive transform coding. To this end, we introduce a novel framework that eliminates the need to signal graph information to the decoder to recover the coefficients. This is accomplished by computing the GBT using predicted residual blocks, which are predicted by a modeling approach that employs only the reference samples and information about the prediction mode. Evaluation results on several pathology images, in terms of the energy preserved and MSE when a small percentage of the largest coefficients are used for reconstruction, show that the GBT can outperform the DST and DCT.

1. Introduction

Thanks to the introduction of high-throughput slide scanners, microscope glass slides can now be digitized to produce color images, which are called whole-slide images (WSIs). This has fueled the emerging area of digital pathology imaging and resulted in novel ways to share medical imaging data and collaborate remotely [1-2]. WSIs are multi giga-pixel color images that usually require large amounts of bandwidth to be transmitted and stored. Compression is therefore an attractive solution for data access and transmission of these images [3-7]. Recent proposals in this area include lossless compression methods based on the intra-prediction mode of the High Efficiency Video Coding (HEVC) standard [4,8], and lossy methods based on the JPEG2000 standard [7,9]. Although lossless compression guarantees perfect reconstruction of the image, it fails to attain high compression ratios. Lossy compression is then more advisable, especially since it has been shown that compression ratios of up to 60:1 can be used on WSIs without negatively affecting the diagnosis process [7].

Lossy compression methods are based on the principle of expanding a signal into orthonormal bases using an orthogonal transform, with the expectation that most information is captured by a few basis functions. Quantization is then applied to the resulting coefficients. For a random signal with a known covariance function, it is well known that the Karhunen Loève transform (KLT) is the linear transform with the best energy compaction property. The KLT basis functions of camera-captured images are close to the Discrete Cosine Transform (DCT), thus the DCT has been championed as the best suited transform for compression applications. Unfortunately, the DCT offers little adaptability to the characteristics of the signal, as a fixed transform is applied to all signals.

The Graph-Based Transform (GBT) has been recently shown to attain promising results for data de-correlation and energy compaction. This comes as an intrinsic consequence of the underlying graph structure, which can accurately reflect the correlation among pixels [10]. In general, there two variants of GBTs. The first one is constructed based on the specific graph representing the signal to be transformed. This variant accurately reflects the characteristics of the signal, but may require signaling additional information so the decoder can reconstruct the graph [11]. The second variant consists in using separable transforms that can be applied to rows and columns of a matrix of signal values (i.e., a pixel block) [12]. This may require understanding the characteristics of the data from training data, but requires no additional information to be signaled to the decoder. Although several works may be found in the literature on the performance of the GBT for residual data of camera-captured imagery generated by block-based predictive transform coding (PTC) methods, such as the inter- and intra-coding modes of HEVC, no work is available on the suitability of the GBT for compression of WSIs. This paper then focuses on the first variant of GBTs and its performance for data de-correlation and energy compaction of WSIs, within the context of block-based PTC using intra-prediction. Specifically, we introduce a new framework that eliminates the need to signal additional information to the decoder. This is achieved by computing the GBT based on a predicted residual signal, which is computed using only the reference samples used to predict a block. This framework is evaluated on a wide range of pathology images depicting different tissue types. Results are reported in terms of the energy compaction properties of the GBT and the Mean Squared Error (MSE) of the reconstructed images. The results are compared to those attained by the KLT, DCT, GBT when information is needed to be signaled to the decoder, and the Discrete Sine Transform (DST), as implemented in the intra-prediction mode of HEVC [13]. Evaluations show that the GBT attains better energy compaction properties than the DST and the DCT for the evaluated pathology images, with a very similar performance in terms of MSE.

The rest of the paper is organized as follows. Section 2 briefly introduces the variant of GBTs used in this work. In Section 3, we explain in detail the proposed framework. The experimental results are presented in Section 4. Section 5 draws conclusions and presents ideas for future work.

2. Graph-based Transform

Within the context of block-based PTC, the GBT is usually constructed by eigen-decomposition of the combinatorial Laplacian, \mathbf{L} , of the undirected graph $G = (V, E, \mathbf{A})$, representing the residual signal, \mathbf{s} , of a block, where each node in the finite set V , i.e., $v_n \in V$, represents a sample location, E is the set of weighted edges connecting nodes, and \mathbf{A} is a symmetric weighted adjacency matrix. If there is an edge $e = (i, j)$ connecting pixel locations i and j , the entry \mathbf{A}_{ij} represents the weight of the edge; otherwise, $\mathbf{A}_{ij} = 0$, with $\mathbf{A}_{ij} = \mathbf{A}_{ji}$. Large values in \mathbf{A} usually represent a high similarity between the connected nodes, according to a given criterion. Matrix \mathbf{L} , also called the (un-normalized) graph Laplacian is computed as $\mathbf{L} = \mathbf{D} - \mathbf{A}$, where the degree matrix, \mathbf{D} , is a diagonal matrix whose i^{th} diagonal element, d_i , is equal to the sum of the weights of all the edges incident to node i . Since \mathbf{L} is a real symmetric matrix, it has a complete set of orthonormal eigenvectors with associated real, non-negative eigenvalues. Therefore, the eigen-decomposition of \mathbf{L} can be used as an orthogonal transform for the residual signal. Let us

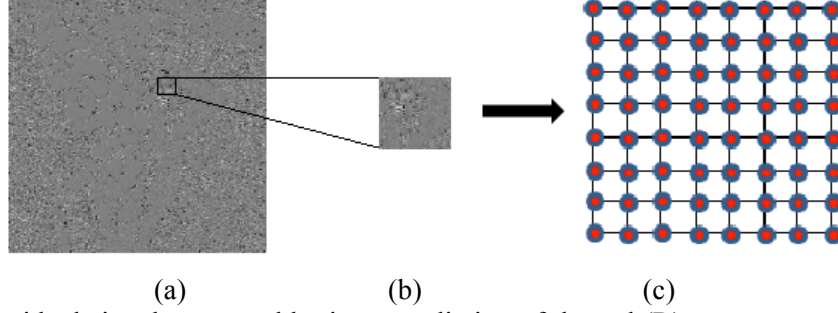


Fig. 1. (a) Residual signal generated by intra-prediction of the red (R) component of a pathology image depicting lymphatic tissue. (b) 8×8 residual block and (c) corresponding 4-connected graph.

denote the eigen-system of \mathbf{L} by $\{(\lambda_i, \mathbf{v}_i)\}$, where λ_i/\mathbf{v}_i is the i th eigenvalue/eigenvector pair, and \mathbf{V} is the set of eigenvectors. Analogous to the classical Fourier transform, one can define the GBT, $\hat{\mathbf{s}}$, of signal $\mathbf{s} \in \mathbb{R}^N$, which resides on the nodes of G , as the expansion of \mathbf{s} in terms of the eigenvectors of \mathbf{L} :

$$\hat{\mathbf{s}}(\lambda_i) = \langle \mathbf{s}, \mathbf{v}_i \rangle = \sum_{k=0}^{|\mathbf{V}|-1} \mathbf{s}(k) \mathbf{v}_i(k) = \mathbf{F} \mathbf{s}, \quad (1)$$

where $\mathbf{F} = \mathbf{V}^{-1}$ is the graph Fourier transform and the set of eigenvalues of \mathbf{L} , denoted by $\sigma(\mathbf{L}) = \{\lambda_0, \lambda_1, \dots, \lambda_{N-1}\}$, is the entire corresponding spectrum. The original signal can be reconstructed by the inverse GBT, which is given by $\mathbf{s} = \mathbf{F}^{-1} \hat{\mathbf{s}} = \mathbf{V} \hat{\mathbf{s}}$.

In this work, each $N \times N$ residual block is represented by a 4-connected graph (see Fig. 1), and the weight of the edge connecting nodes a and b is computed using a Gaussian kernel weighing function, as follows:

$$W_{a,b} = \begin{cases} \exp\left(-\frac{[\text{dist}(a,b)]^2}{2\theta^2}\right) & \text{if } \text{dist}(a,b) \leq k, \\ 0 & \text{otherwise} \end{cases}, \quad (2)$$

where $\text{dist}(a,b)$ represents the Euclidian distance between the residual value associated with nodes a and b , θ is the kernel's width, and k is a parameter.

3. Proposed Framework

Our proposed framework assumes a block-based PTC method that employs the set of prediction modes currently used in the HEVC standard. This set comprises 33 angular prediction modes that model 33 different directional patterns; a DC mode and a PLANAR mode that generate smooth surfaces. Fig. 2(a) illustrates the prediction directions associated with the angular modes. The basic prediction principle for all angular modes is exemplified in Fig. 2(b).

Our framework is depicted in Fig. 3. At the encoder side, we employ a prediction inaccuracy modelling to predict the residual block for each $N \times N$ block by only using the prediction mode selected by the encoder and the references samples of the block [14]. Each predicted residual block is represented by a 4-connected weighted graph and the corresponding GBT is computed by eigen-decomposition, as detailed in Section 2. This GBT is then used to transform the actual residual block. Coefficients may then be quantized and subsequently entropy coded. At the decoder side, we re-compute the predicted residual block as done by the encoder. Note that this is possible without having to signal any

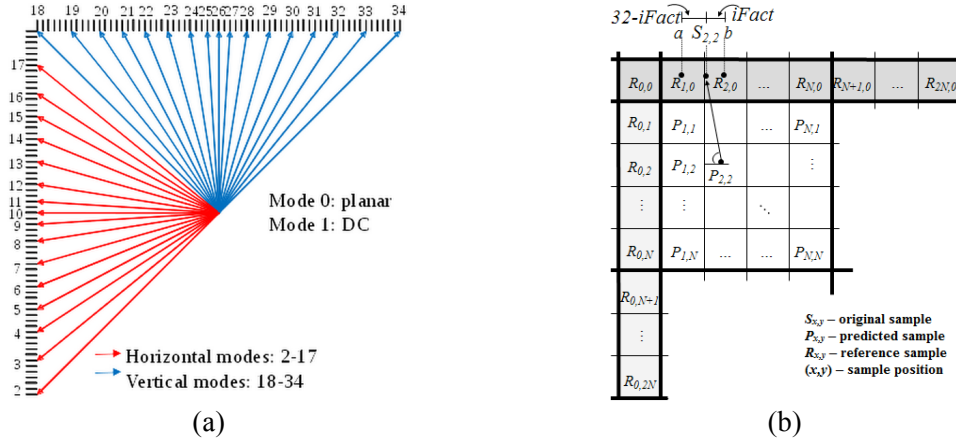


Fig. 2. (a) Intra prediction modes in HEVC. (b) Example of the prediction principle using interpolation at 1/32-pixel accuracy. $iFact$ is the distance between sample $S_{x,y}$ and reference sample b . Reference samples are: $\{R_{0,1}, R_{0,2}, \dots, R_{0,2N}\}$ – located to the left of the current block, and $\{R_{0,0}, R_{1,0}, \dots, R_{2N,0}\}$ – located above of the current block.

additional information, as the reference samples and prediction mode of each block are readily available at the decoder. Based on the predicted residual block, the corresponding 4-connected weighted graph and GBT is computed, which allow us to compute the inverse GBT to be applied to the decoded coefficients (after entropy decoding) and obtain the reconstructed residual block. Finally, the predicted block and re-constructed residual block are added to obtain the reconstructed block.

The prediction inaccuracy modeling for the residual blocks computed by employing any of the 33 angular modes depicted in Fig 2 is based on the work by X. Cai *et. al* in [15]. This modeling approach predicts a residual block using the reference samples to the left and above the block, and the information about the angular mode used by the encoder. The approach is based on the argument that residual blocks computed after angular intra-prediction can be approximated by using the gradient of reference samples and the distance between the position of the reference samples used and the position of the value to be approximated within a block. For horizontal modes, i.e., modes 2-17 in Fig. 2(a), the predicted residual signal, at position (x, y) within an $N \times N$ block is approximated as follows:

$$res(x, y) \approx \frac{P}{\cos \alpha} \frac{\partial f(0, y)}{\partial y} \Big|_y, \quad \theta(x, y), \quad (3)$$

where $\theta(x, y)$ is the angle between two consecutive reference samples to the left and depends on the position being predicted, $\frac{\partial f(0, y)}{\partial y}$ denotes a partial derivative with respect to the reference samples to the left, P is the distance between the reference sample $f(0, y')$ and the position to be predicted, which is calculated as $P^2 = R^2 + Q^2$; and α is the angle between P and the horizontal. Fig. 4(a) graphically represents the variables used in Eq. 3. For the vertical modes, e.g., modes 18-34 in Fig. 2(a), the same calculations can be applied by appropriately rotating the block, as depicted in Fig. 4(b).

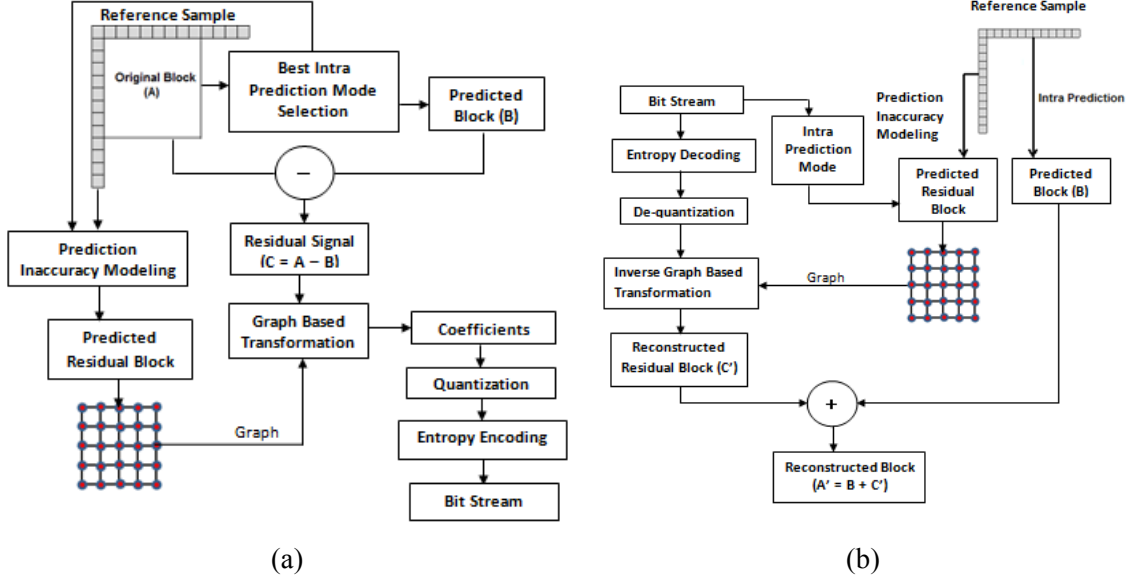


Fig. 3. Block diagram of the proposed framework for (a) encoding and (b) decoding.

For the DC and PLANAR modes, we propose an extension to the model proposed in [15]. In the case of the DC mode, we note that residual values tend to increase in the horizontal, vertical and diagonal direction proportionally to the distance from the reference samples, since the predicted value is computed as the average of all reference samples located above and to the left of the block. This is based on the observation that samples in the first row and first column of the block are expected to have a more similar value to that of the reference samples than those samples located far from them. Our proposed modeling approach is based on this observation. Specifically, for the DC mode we propose to average the prediction for the pure horizontal mode (10), pure vertical mode (26), and diagonal mode (18), as follows:

$$resDC(x, y) \approx (resH(x, y) + resV(x, y) + 2 \cdot resD(x, y)) \gg 2 \quad (4)$$

$$resH(x, y) \approx R_1 \frac{\partial f(0, y)}{\partial y} \Big|_{y'} \theta_1(x, y) \quad (5)$$

$$resV(x, y) \approx R_2 \frac{\partial f(x, 0)}{\partial x} \Big|_{x'} \theta_2(x, y) \quad (6)$$

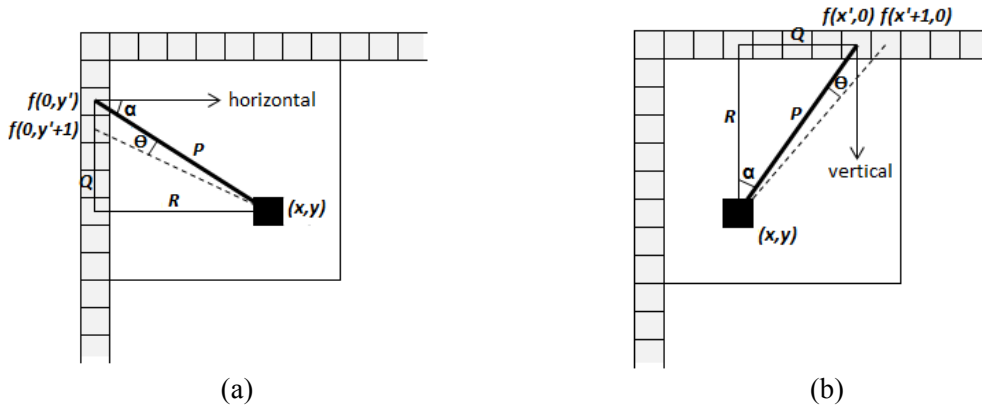


Fig. 4. Prediction inaccuracy modeling for the (a) horizontal and (b) vertical angular modes.

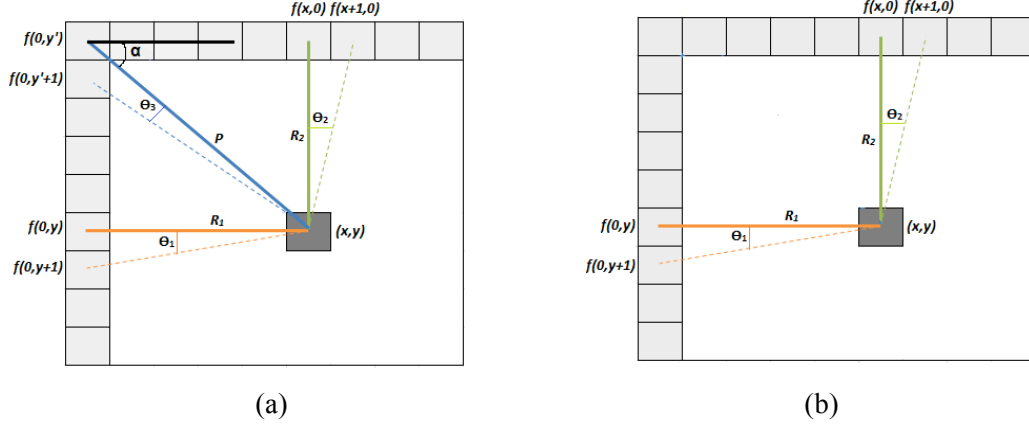


Fig. 5. (a) Model for the DC mode and (b) the Planar mode

$$resD(x, y) \approx \frac{P}{\cos(\frac{\pi}{4})} \frac{\partial f(0, y)}{\partial y} \Big|_{y'} \Theta_3(x, y) \quad (7)$$

where $resH(x, y)$, $resV(x, y)$, $resD(x, y)$ are the predicted residual values in the horizontal, vertical and diagonal directions, respectively, \gg represents a bit shift to the right, R_1 and R_2 are the distances between the predicted position and the references samples to the left and above, respectively. Note that the modeling approach in Eq. 7 is just a case of Eq. 3 when $\alpha = \pi/4$. The modeling approach for the DC mode is depicted in Fig. 5(a) and exemplified in Fig. 6 by using an example 4×4 block, where the average of all reference samples is 155. From Fig. 6, it can be observed that the residual signal indeed tends to increase for samples located far from the reference samples. Our prediction inaccuracy modelling effectively approximates the residual based on this observation.

In the case of the PLANAR mode, we follow a similar approach to the one followed for the DC mode [see Fig. 5(b)]. Specifically, we propose to average the prediction for the pure horizontal mode (10) and pure vertical mode (26), as follows:

$$resPlanar(x, y) \approx (resH(x, y) + resV(x, y)) \gg 1. \quad (8)$$

Fig. 7 depicts the G component of a sample pathology image and the corresponding predicted signal after intra-prediction using the DC and PLANAR modes. Fig. 7 also depicts the corresponding residual signal and predicted residual signal obtained by the proposed prediction inaccuracy modeling for the DC and PLANAR modes.

102	113	131	211	200
132	128	131	165	189
169	155	156	168	203
183	160	163	172	205
154	172	178	184	212

(a)

155	155	155	155
155	155	155	155
155	155	155	155
155	155	155	155

(b)

-27	-24	10	34
0	1	13	48
5	8	17	50
17	23	29	57

(c)

-18	-15	8	44
-5	-2	11	47
7	1	19	55
17	23	29	63

(d)

Fig. 6. Illustration of the proposed modeling approach for the DC mode. The average of all reference samples is 155. (a) Original block, (b) predicted block, (c) actual residual block and (d) predicted residual block.

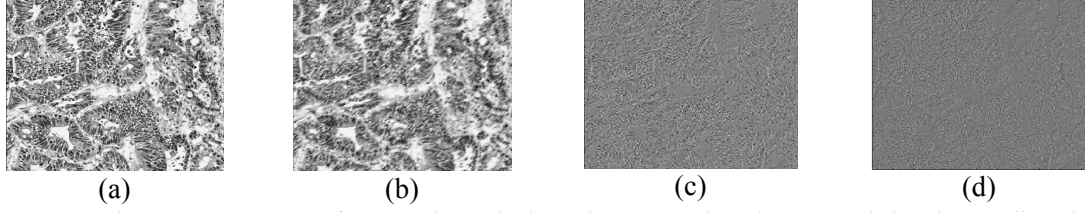


Fig. 7. (a) The G component of a sample pathology image (colon tissue) and the (b) predicted, (c) residual, and (d) predicted residual signals. Only the DC and Planar modes are used for prediction.

4. Performance Evaluation

The proposed framework is tested on ten 1024×1024 sections of WSIs depicting lymphatic, pancreatic, colon and brain tissue. The images are obtained from the Center for Biomedical Informatics and Information Technology of the US National Cancer Institute [16]. We employ intra-prediction using all 35 modes depicted in Fig. 2, with a block size of 8×8 on the G component. We compare the performance of the GBT using our framework (GBT-P) against the GBT when the graphs are computed using the actual residual blocks (GBT-A), the DCT and the DST, as implemented in HEVC. The performance of all transforms is measured in terms of the energy preserved by reconstructing the image using a sub-set of the largest coefficients and the corresponding MSE. In other words, we evaluate the energy compaction properties of the transforms and the quality of the reconstructed images. The coefficients are selected by setting a threshold that indicates the minimum absolute value that the coefficients in the sub-set must have. A large threshold allows to include the largest coefficients in the sub-set, while a threshold close to zero results in including most of the coefficients in the sub-set. By gradually decreasing an initial large threshold, this approach gradually includes in the sub-set the largest coefficients. Note that this approach differs from one that selects the DC and low frequency AC coefficients first, and gradually include the high frequency AC coefficients. The approach used in this work allows selecting the largest coefficients, regardless of their frequency type. This is advantageous for pathology images, as they usually depict strong edges and non-smooth regions, resulting in several AC coefficients with large values. Our evaluations also include the KLT, as the baseline transform. Table 1 tabulates the average energy preserved, in percentage, by the transforms and the corresponding average MSE values, for all evaluated images, using a small percentage of coefficients, ranging from 1% to 10%.

Table 1. Average preserved energy (PE - %) and MSE using a small percentage of coefficients.

Transform	Percentage of coefficients used									
	1%		3%		5%		7%		10%	
	PE	MSE	PE	MSE	PE	MSE	PE	MSE	PE	MSE
KLT	55.20	44.80	88.07	12.81	89.79	11.50	81.07	10.46	92.58	9.25
DCT	19.71	80.24	46.06	54.33	59.80	40.74	68.75	31.82	77.59	22.99
GBT-A	19.73	80.35	46.11	54.48	59.86	40.88	68.80	31.97	77.62	23.16
GBT-P	19.72	80.36	46.08	54.51	59.82	40.92	68.77	32.01	77.61	23.19
DST	17.69	80.25	45.51	54.81	58.67	41.74	67.27	33.14	75.92	24.53

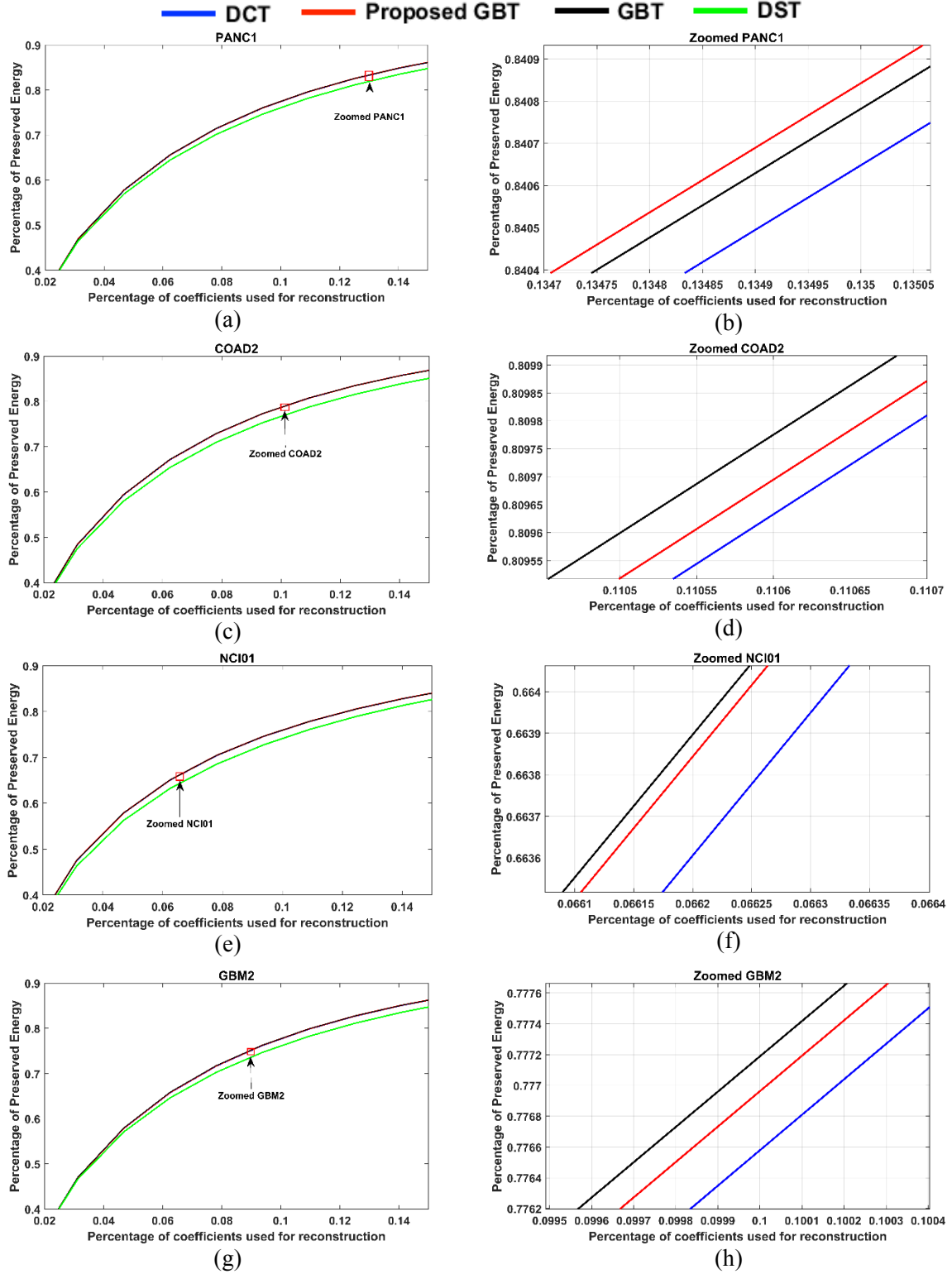


Fig. 8. Energy compaction performance of different transforms for digital pathology images depicting (a-b) pancreatic tissue, (c-d) colon tissue, (e-f) lymphatic tissue, and (g-h) brain tissue.

As expected, the KLT provides the best performance. Note that the GBT-A outperforms the GBT-P. This is also expected as the GBT-A is constructed based on the graphs of the actual residual signals. However, it is important to recall that the GBT-A requires signaling information about the graphs to the decoder. The GBT-P outperforms the DST in terms of preserved energy, which is used in HEVC for intra-predicted residuals. For example, on average, 11.47% more energy can be preserved by the GBT-P than the DST by using only 1.0% of the coefficients. In terms of MSE values, the GBT-P attains lower values than the DST for most of the cases tabulated in Table 1. Note that the GBT-P slightly outperforms the DCT in terms of preserved energy, for all percentages of coefficients tabulated in Table 1. However, the corresponding average MSE values are slightly higher than those attained by DCT. Fig. 8 plots the percentage of preserved energy vs. the percentage of coefficients used for four different images. The improvements of the GBT-P over the DST and the DCT can be visually appreciated in these plots.

5. Conclusions and Future Work

WSIs are multigiga-pixel color images that usually require large amounts of bandwidth to be transmitted and stored. To facilitate the widespread of these images in clinical settings, compression is needed to reduce storage and bandwidth requirements. Block-based PTC using intra-prediction has been shown to be capable of efficiently compress these images. In this paper, we presented a framework that allows employing the GBT to transform intra-predicted residual signals of these images without the need to signal information about the graphs to the decoder. The framework is based on computing the necessary graphs using predicted residual blocks, which can be re-computed at the decoder using only the reference samples and information about the prediction mode used. We evaluated the performance of the GBT computed in this fashion in terms of the energy preserved and MSE when a small percentage of the largest coefficients are used for reconstruction of several pathology images. Evaluation results show that the GBT can outperform the DST, while slightly outperforming the DCT, in terms of energy preserved, for the evaluated images.

Our future work includes determining the effect of graph construction on the energy compaction properties of the GBT. The connectivity pattern representing the correlation among residual samples is an important factor that may influence the properties of the GBT, and correlations between reference samples and those to be predicted should be also considered. Our future work also includes improving the prediction inaccuracy modeling to more accurately predict residual blocks.

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